## CMG-3T CALIBRATION SHEET

WORKS ORDER:	5169	DATE:	27-Jul-2009
SERIAL NUMBER:	T36047	TESTED BY:	S. Goddard
	Velocity Output V/m/s (Differential)	Mass Position Output (Acceleration output) V/m/s <sup>2</sup>	Feedback Coil Constant Amp/m/s <sup>2</sup>
VERTICAL	2 x 743	1757	0.02342
NORTH/SOUTH	2 x 749	1993	0.02657
EAST/WEST	2 x 752	1964	0.02618
Power Consumption: Calibration Resistor:	60mA @ +12V inpu 51000	t	

NOTE: A factor of 2 x must be used when the sensor outputs are used differentially (also known as push-pull or balanced output). Under no conditions should the negative outputs be connected to the signal ground. A separate signal ground pin is provided.

## POLES AND ZEROS TABLE

## WORKS ORDER NUMBER: 5169

## **SENSOR SERIAL NO: T36047**

Velocity response output, Vertical Sensor:

IZ

Normalizing factor at 1 Hz: A = 2304000

Sensor Sensitivity: Se

See Calibration Sheet.

Velocity response output, Horizontal Sensors:

POLES (HZ)	ZEROS (HZ)
$-5.89 \ge 10^{-3} \pm j5.89 \ge 10^{-3}$	0
-180	0
-160	
-80	

Normalizing factor at 1 Hz: A =

Sensor Sensitivity:

See Calibration Sheet.

**NOTE:** The above poles and zeros apply to the vertical and the horizontal sensors and are given in units of Hz. To convert to Radian/sec multiply each pole or zero with  $2\pi$ . The normalizing factor A should also be recalculated.

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